

Fall 2015

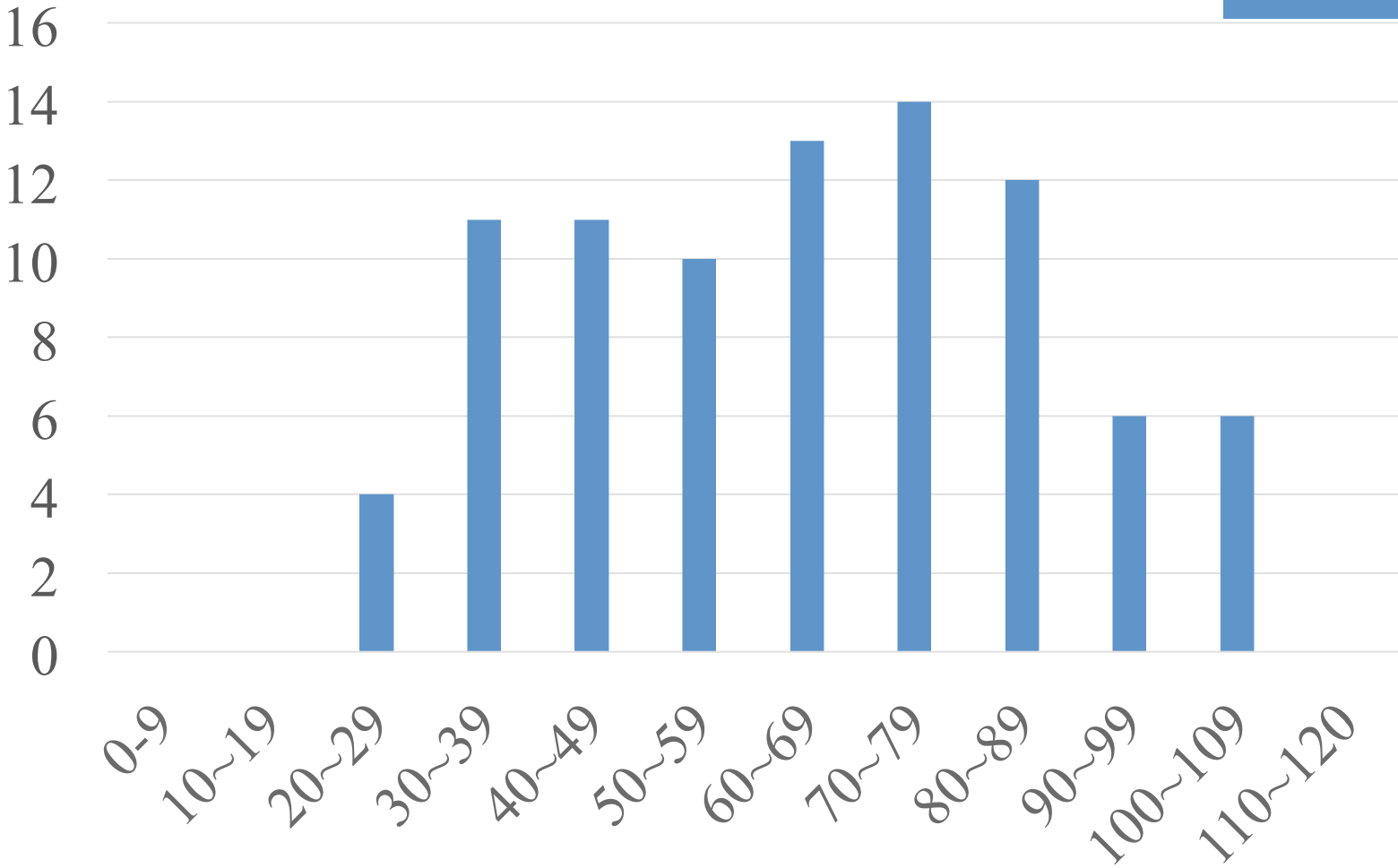
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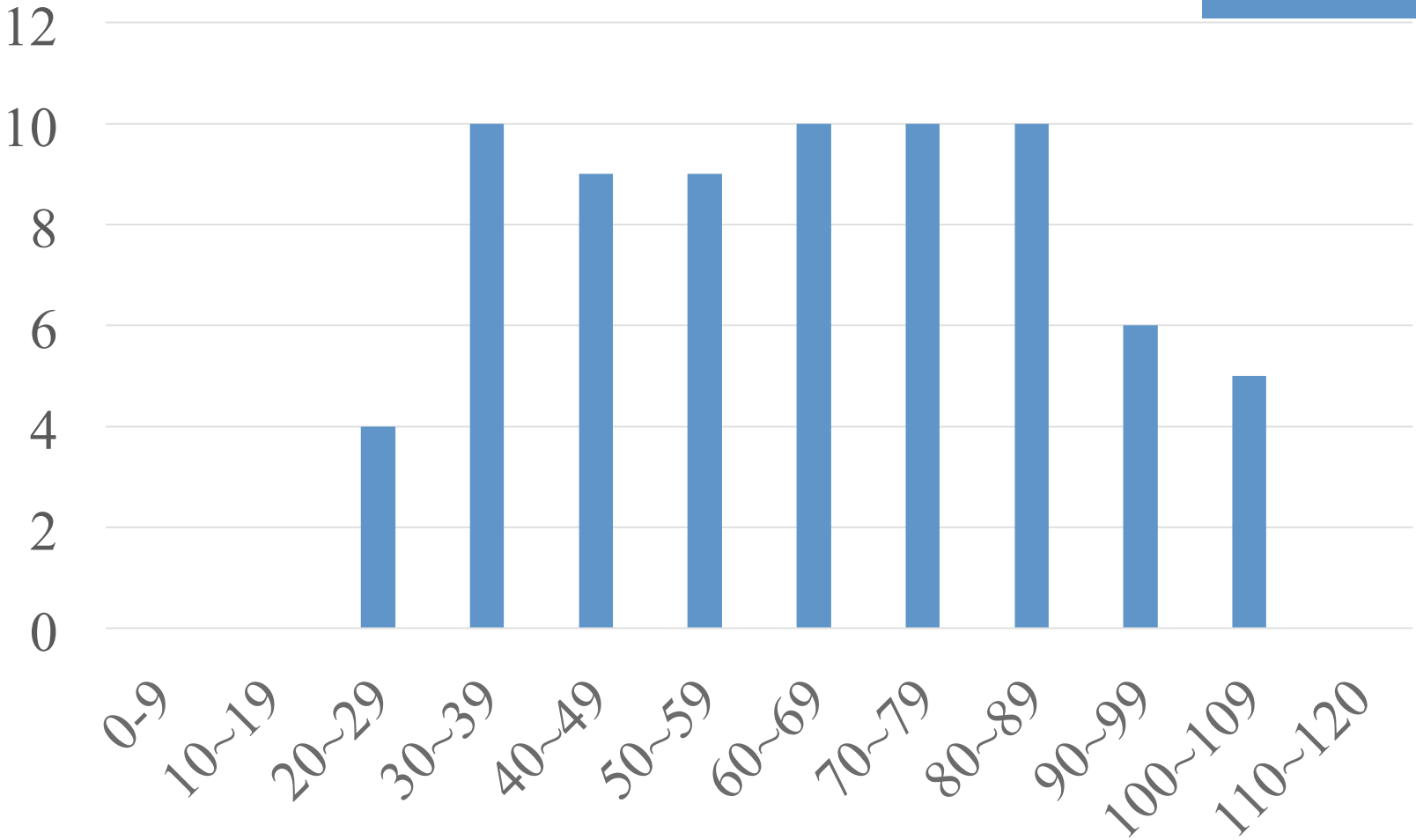
Data Structures

Lecture 11

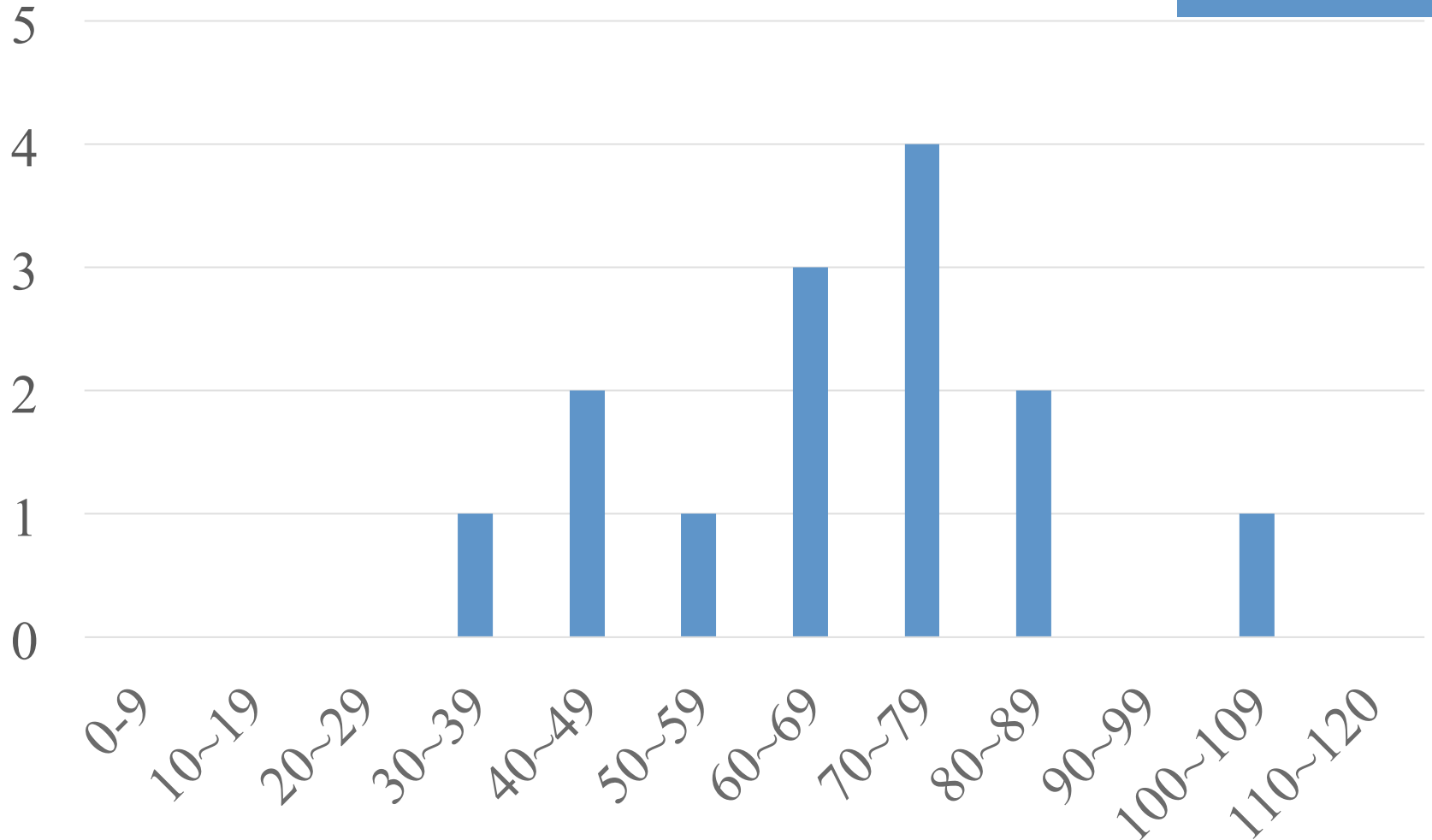
Midterm Mean: 64.60

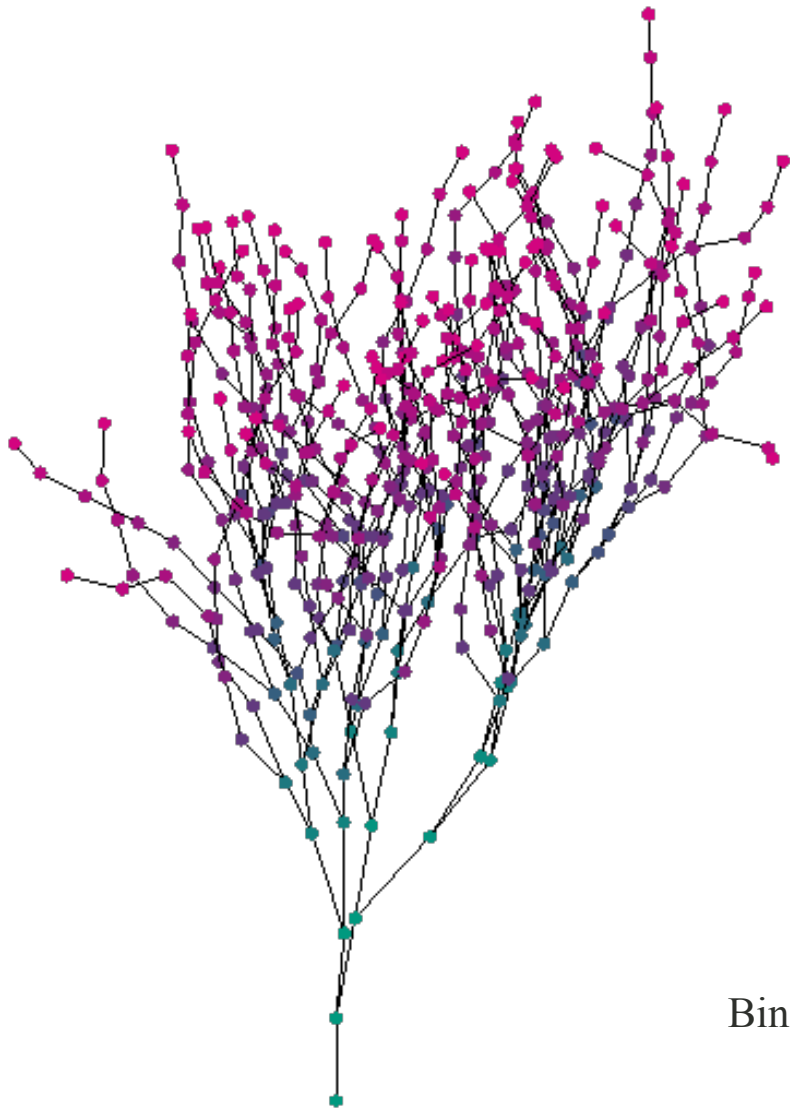


Chinese Session Mean: 63.94



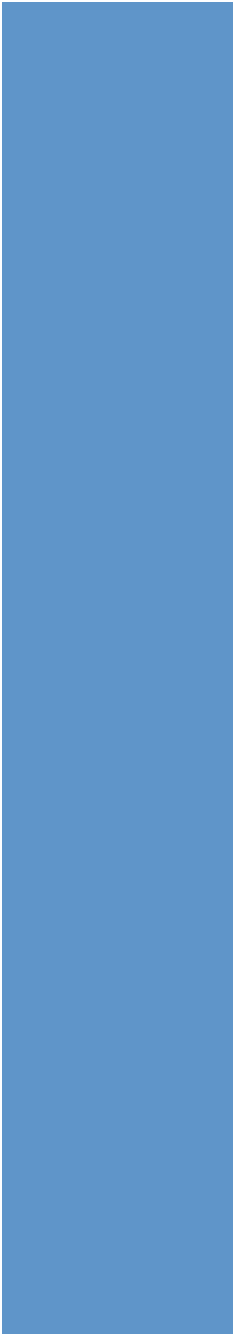
English Session Mean: 68.07





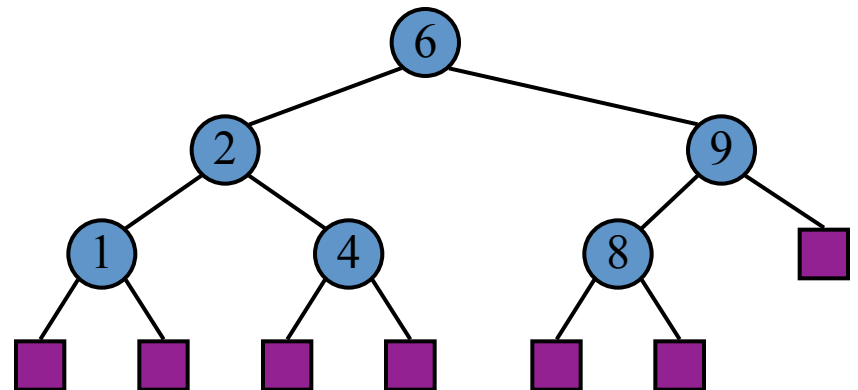
Search Trees

Binary Search Trees, AVL trees, and Splay Trees



Binary Search Trees

- A binary search tree is a binary tree storing keys (or key-value entries) at its internal nodes and satisfying the following property:
 - Let u , v , and w be three nodes such that u is in the left subtree of v and w is in the right subtree of v . We have $key(u) \leq key(v) \leq key(w)$
- External nodes do not store items
- An inorder traversal of a binary search tree visits the keys in an increasing order

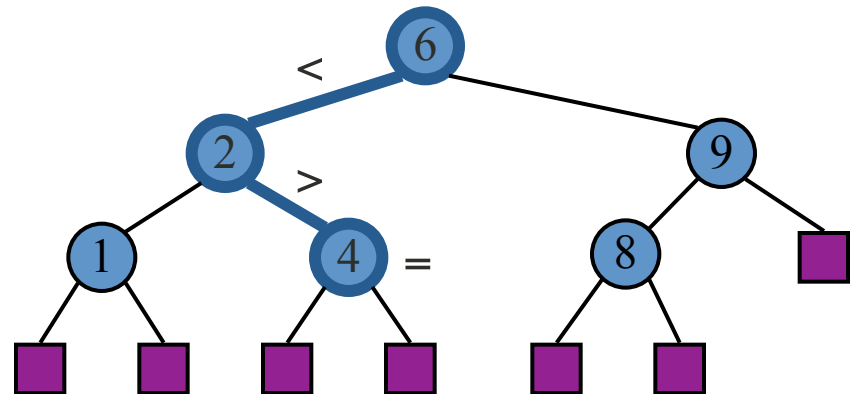


Search

- To search for a key k , we trace a downward path starting at the root
- The next node visited depends on the comparison of k with the key of the current node
- If we reach a leaf, the key is not found
- Example: `get(4)`:
 - Call `TreeSearch(4, root)`
- The algorithms for `floorEntry` and `ceilingEntry` are similar

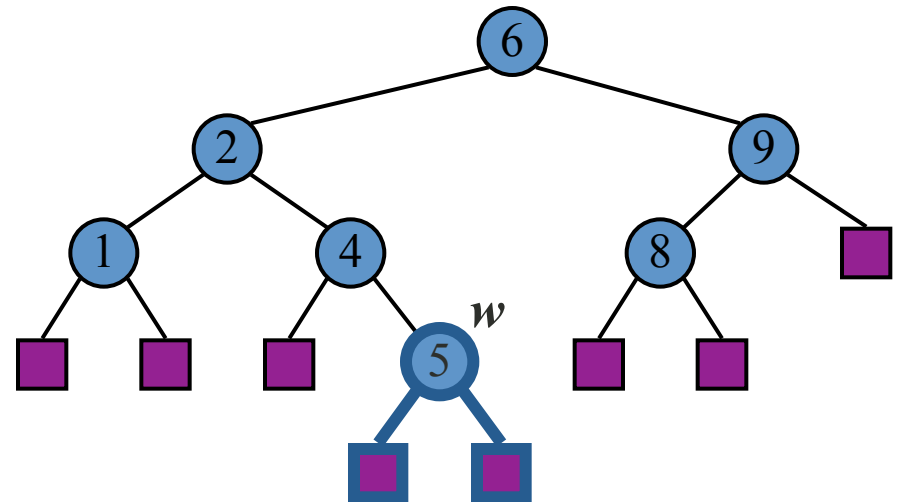
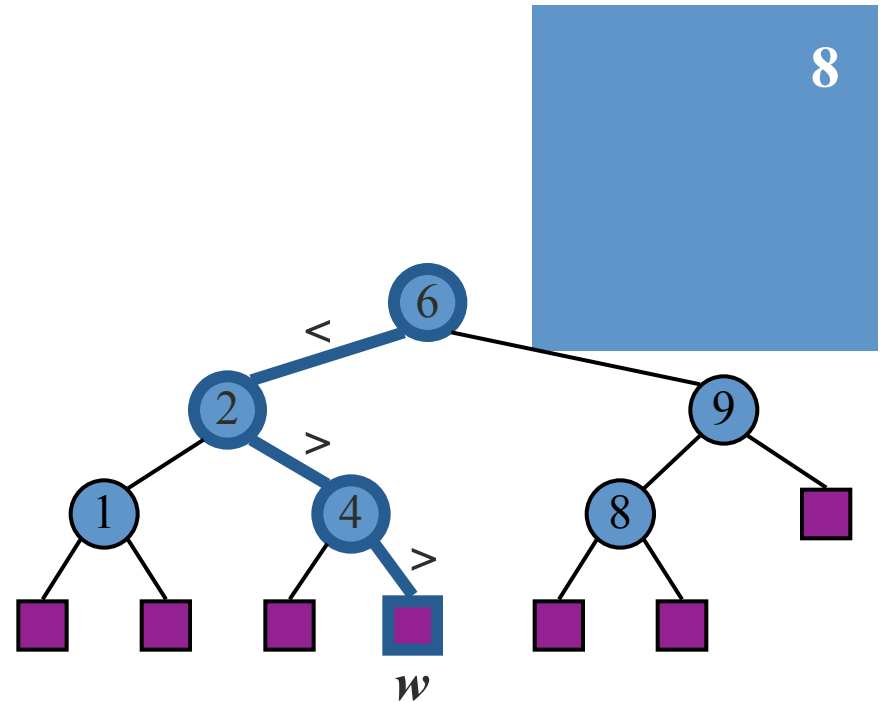
```

Algorithm TreeSearch( $k, v$ )
  if T.isExternal ( $v$ )
    return  $v$ 
  if  $k < \text{key}(v)$ 
    return TreeSearch( $k, T.\text{left}(v)$ )
  else if  $k = \text{key}(v)$ 
    return  $v$ 
  else {  $k > \text{key}(v)$  }
    return TreeSearch( $k, T.\text{right}(v)$ )
  
```



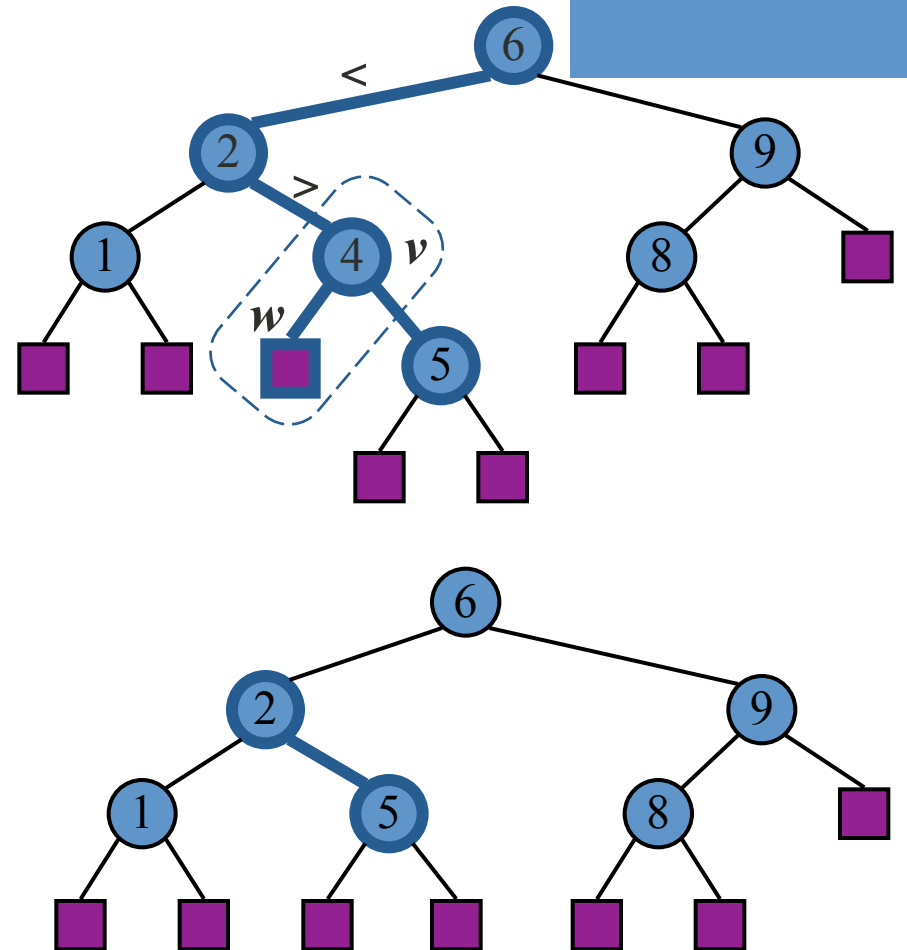
Insertion

- To perform operation $\text{put}(k, o)$, we search for key k (using `TreeSearch`)
- Assume k is not already in the tree, and let w be the leaf reached by the search
- We insert k at node w and expand w into an internal node
- Example: insert 5



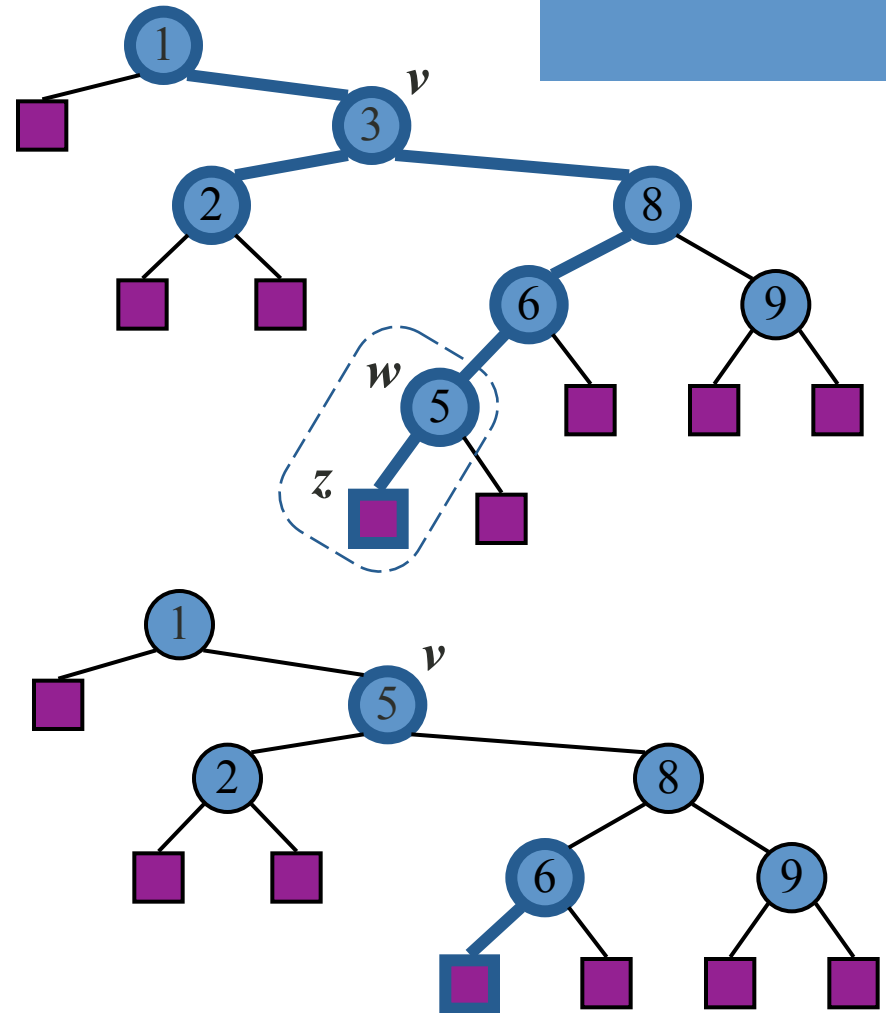
Deletion

- To perform operation $\text{remove}(k)$, we search for key k
- Assume key k is in the tree, and let v be the node storing k
- If node v has a leaf child w , we remove v and w from the tree with operation $\text{removeExternal}(w)$, which removes w and its parent
- Example: remove 4



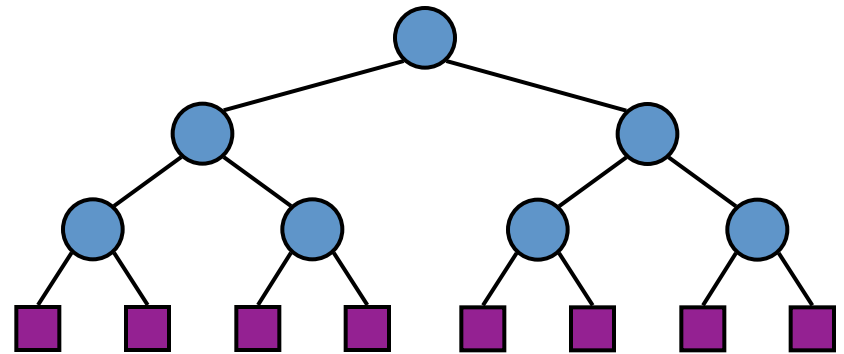
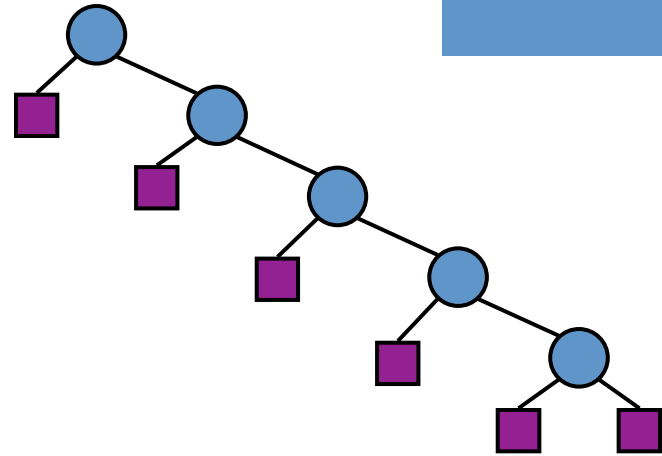
Deletion (cont.)

- We consider the case where the key k to be removed is stored at a node v whose children are both internal
 - we find the internal node w that follows v in an inorder traversal
 - we copy $key(w)$ into node v
 - we remove node w and its left child z (which must be a leaf) by means of operation `removeExternal(z)`
- Example: remove 3



Performance

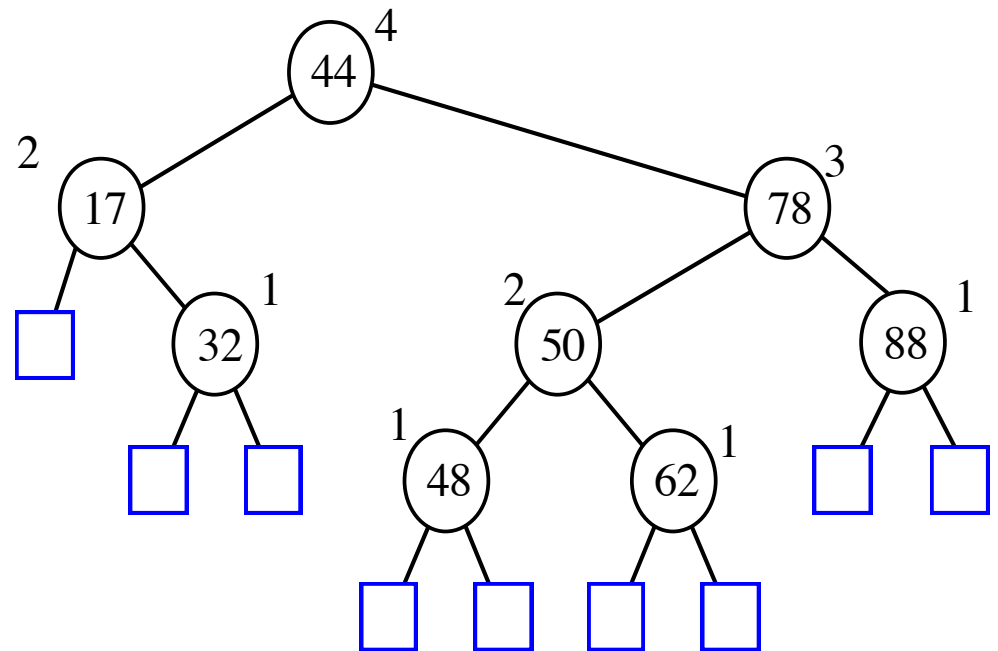
- Consider n ordered set items implemented by means of a binary search tree of height h
 - the space used is $O(n)$
 - methods get, put and remove take $O(h)$ time
- The height h is $O(n)$ in the worst case and $O(\log n)$ in the best case



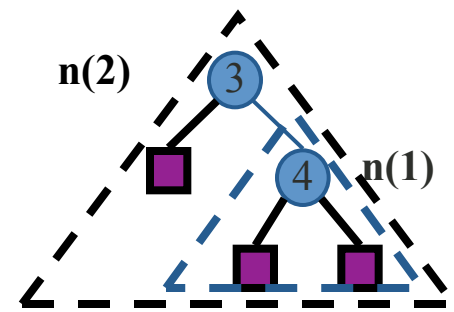
We want a balanced binary tree!

AVL Tree Definition

- AVL trees are balanced
- An AVL Tree is a binary search tree such that for every internal node v of T , the heights of the children of v can differ by at most 1



An example of an AVL tree where the heights are shown next to the nodes:

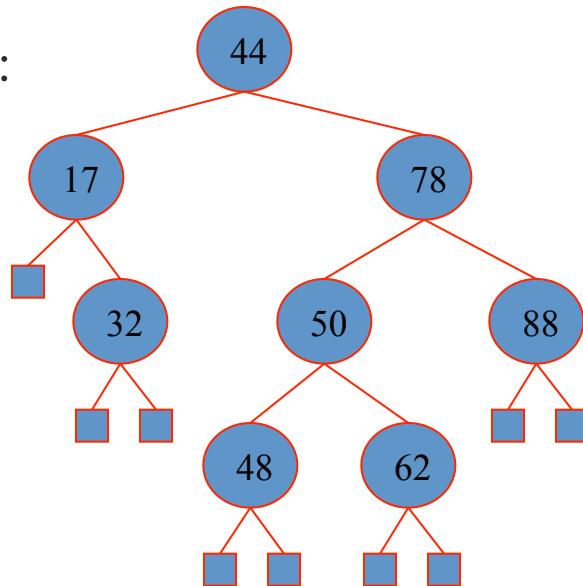


Height of an AVL Tree

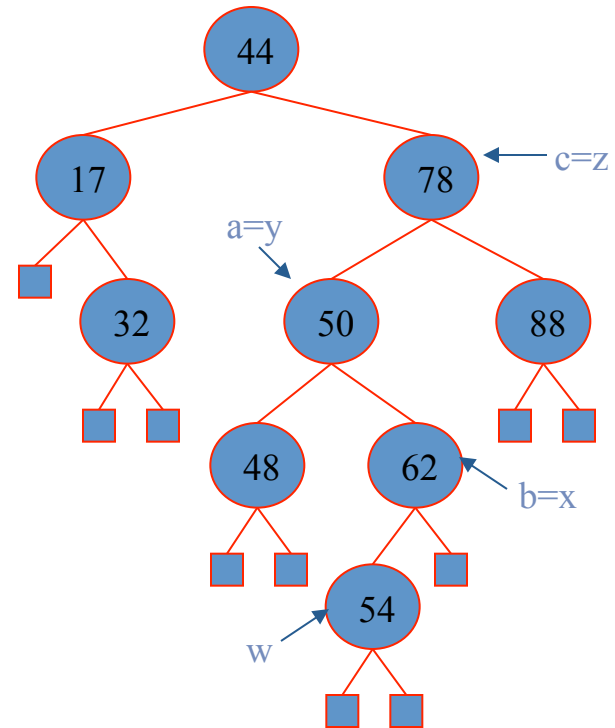
- Fact: The height of an AVL tree storing n keys is $O(\log n)$.
- Proof: Let us bound $n(h)$: the minimum number of internal nodes of an AVL tree of height h .
- We easily see that $n(1) = 1$ and $n(2) = 2$
- For $n > 2$, an AVL tree of height h contains the root node, one AVL subtree of height $n-1$ and another of height $n-2$.
- That is, $n(h) = 1 + n(h-1) + n(h-2)$
- Knowing $n(h-1) > n(h-2)$, we get $n(h) > 2n(h-2)$. So $n(h) > 2n(h-2)$, $n(h) > 4n(h-4)$, $n(h) > 8n(h-6)$, ... (by induction), $n(h) > 2^i n(h-2i)$
- Solving the base case we get: $n(h) > 2^{h/2-1}$
- Taking logarithms: $h < 2\log n(h) + 2$
- Thus the height of an AVL tree is $O(\log n)$

Insertion

- Insertion is as in a binary search tree
- Always done by expanding an external node.
- Example:



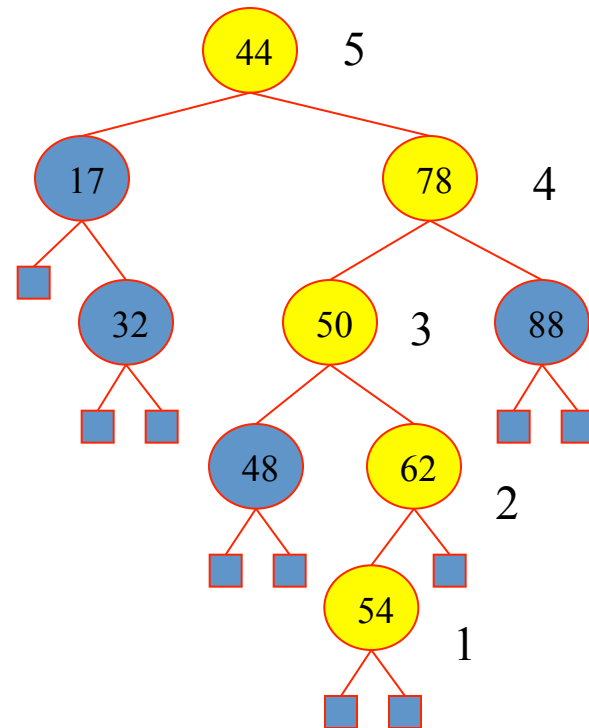
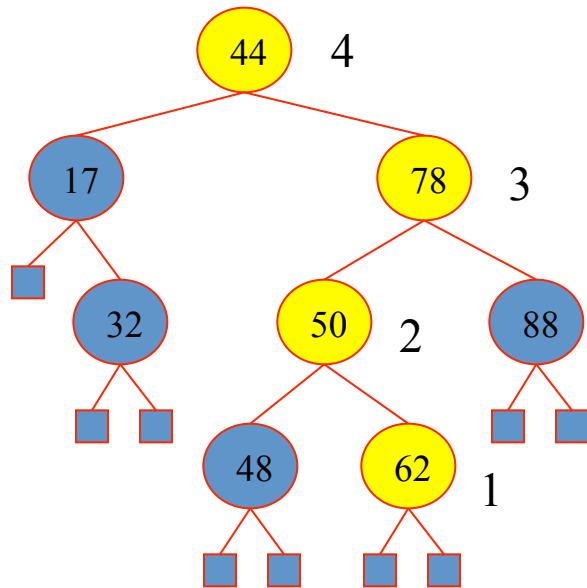
before insertion



after insertion

After Insertion

- All nodes along the path increase their height by 1
- It may violate the AVL property



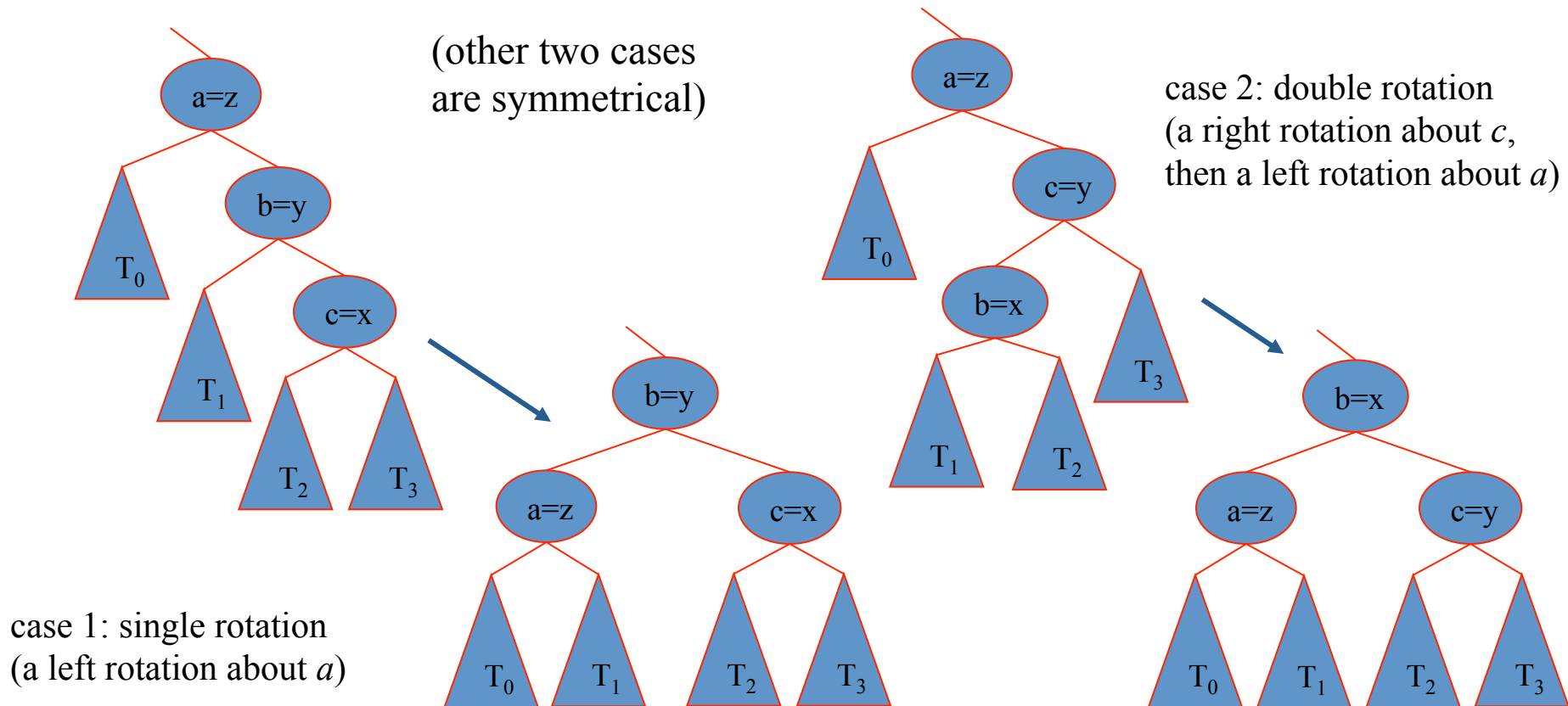
Search and repair

- Let z be the first violation node from the bottom along the path
- Let y be z 's child with the higher height (y is 2 greater than its sibling)
- Let x be y 's child with the higher height
- We rebalance z by calling **trinode restructuring** method



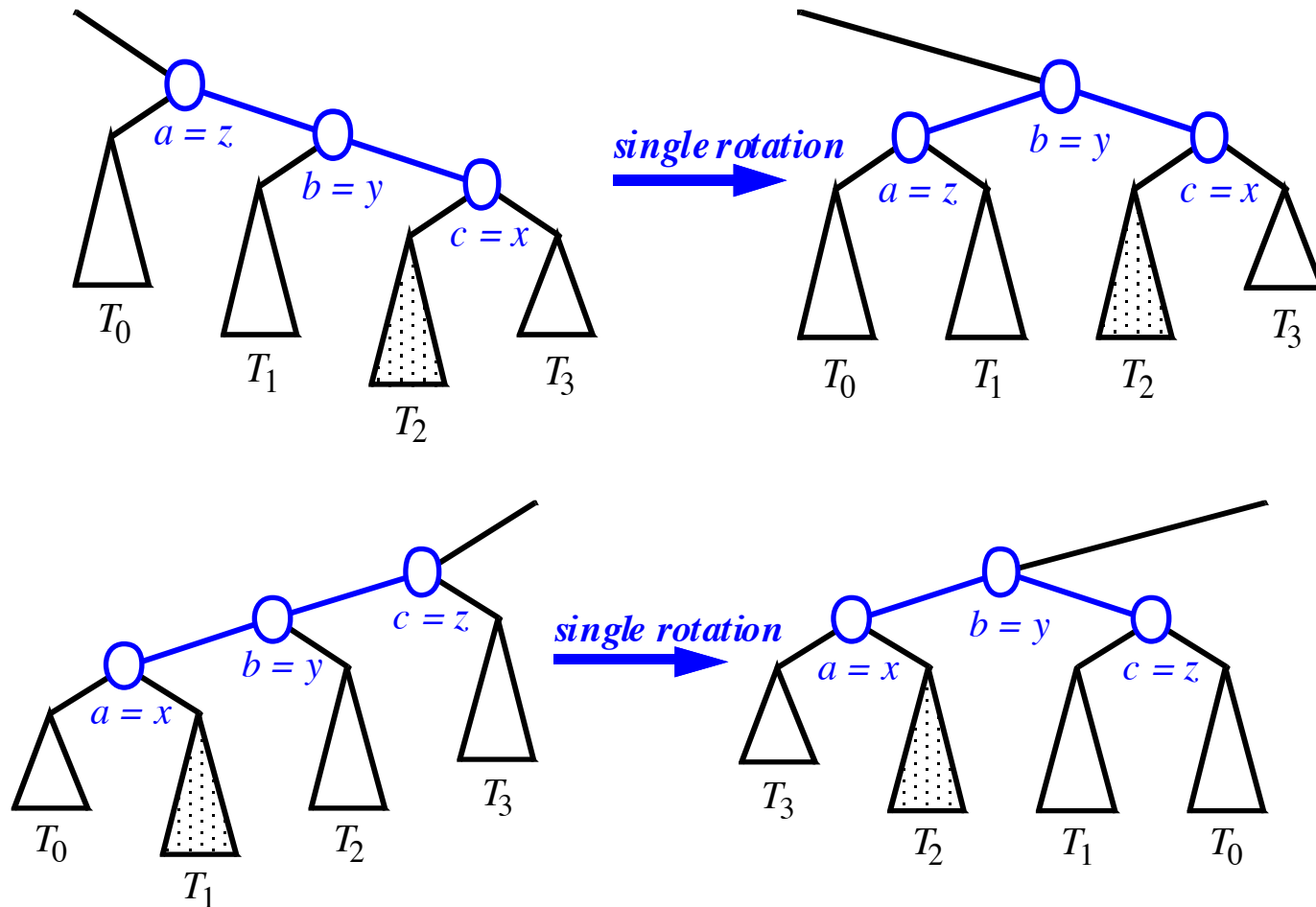
Trinode Restructuring

- let (a,b,c) be an inorder listing of x, y, z
- perform the rotations needed to make b the topmost node of the three



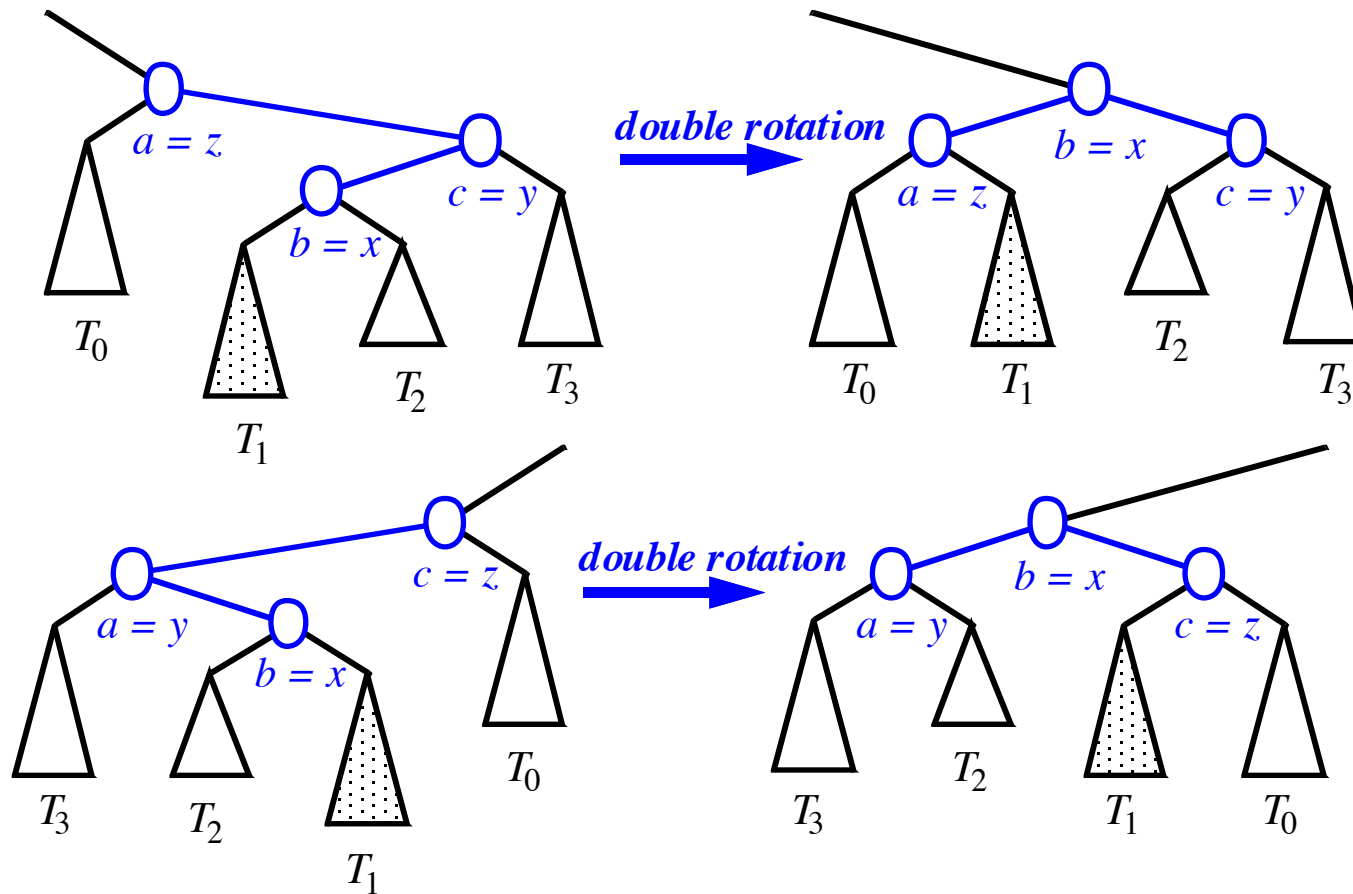
Restructuring (as Single Rotations)

- Single Rotations:

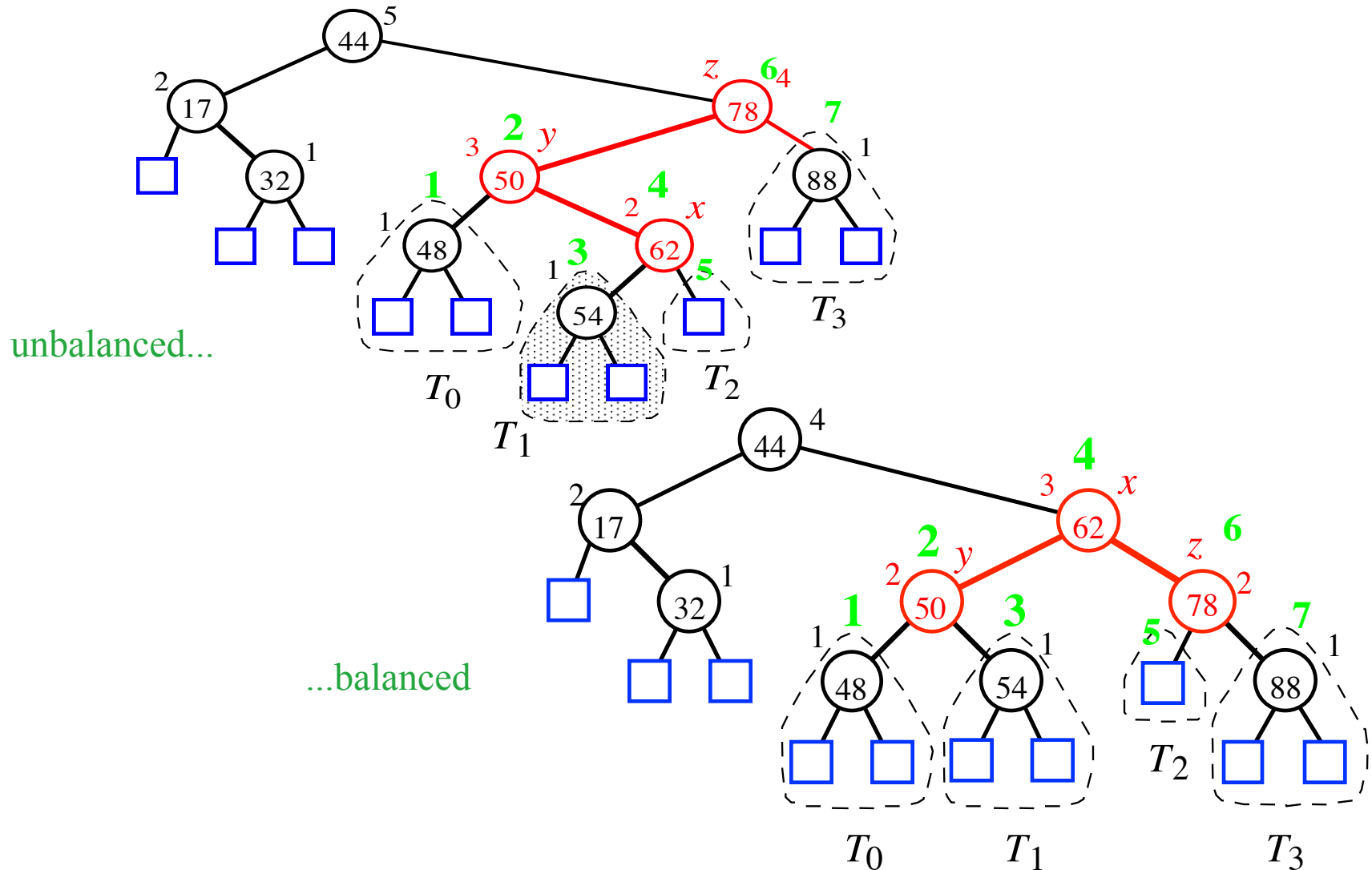


Restructuring (as Double Rotations)

- double rotations:

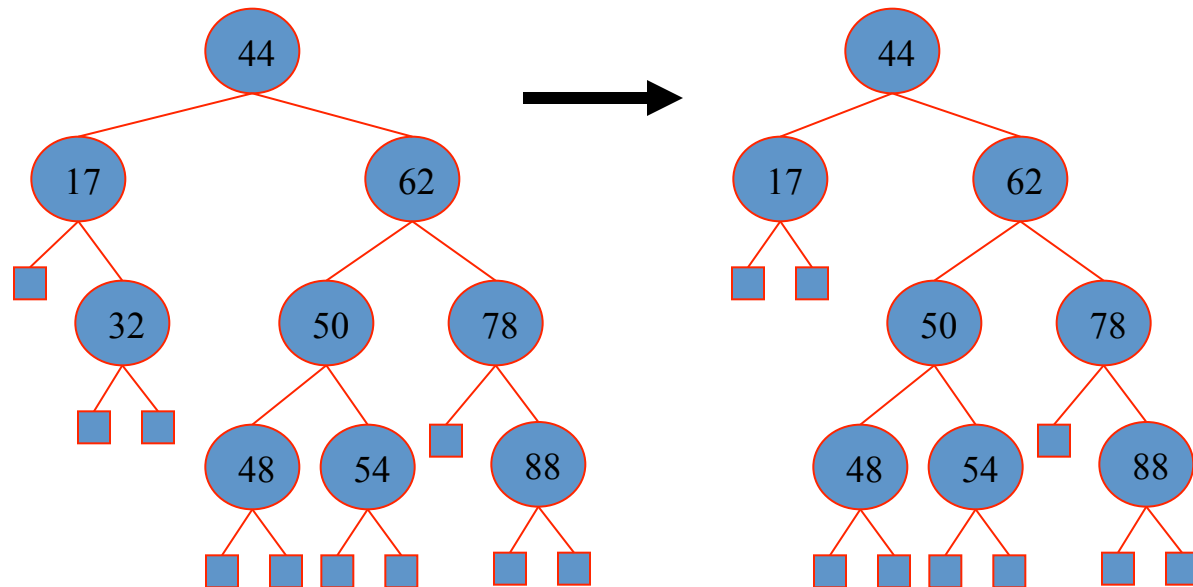


Insertion Example, continued



Removal

- Removal begins as in a binary search tree, which means the node removed will become an empty external node. Its parent, w, may cause an unbalance.
- Example:

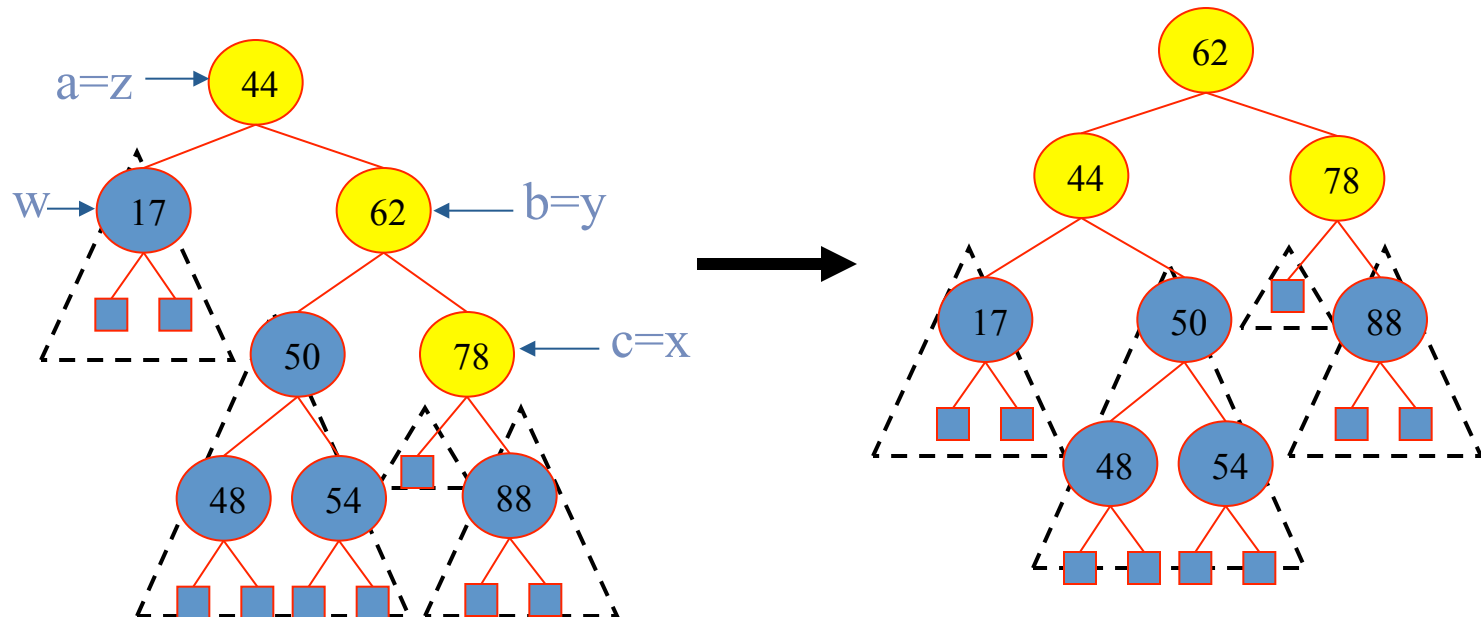


before deletion of 32

after deletion

Rebalancing after a Removal

- Let z be the first unbalanced node encountered while travelling up the tree from w . Also, let y be the child of z with the larger height, and let x be the child of y with the larger height
- As this restructuring may upset the balance of another node higher in the tree, we must continue checking for balance until the root of T is reached



AVL Tree Performance

- a single restructure takes $O(1)$ time
 - using a linked-structure binary tree
- get takes $O(\log n)$ time
 - height of tree is $O(\log n)$, no restructures needed
- put takes $O(\log n)$ time
 - initial find is $O(\log n)$
 - Restructuring up the tree, maintaining heights is $O(\log n)$
- remove takes $O(\log n)$ time
 - initial find is $O(\log n)$
 - Restructuring up the tree, maintaining heights is $O(\log n)$

Splay Tree

- a splay tree is a binary search tree where a node is splayed after it is accessed (for a search or update)
- deepest internal node accessed is splayed
- splay: move the node to the root
- splaying costs $O(h)$, where h is height of the tree – which is still $O(n)$ worst-case
 - $O(h)$ rotations, each of which is $O(1)$

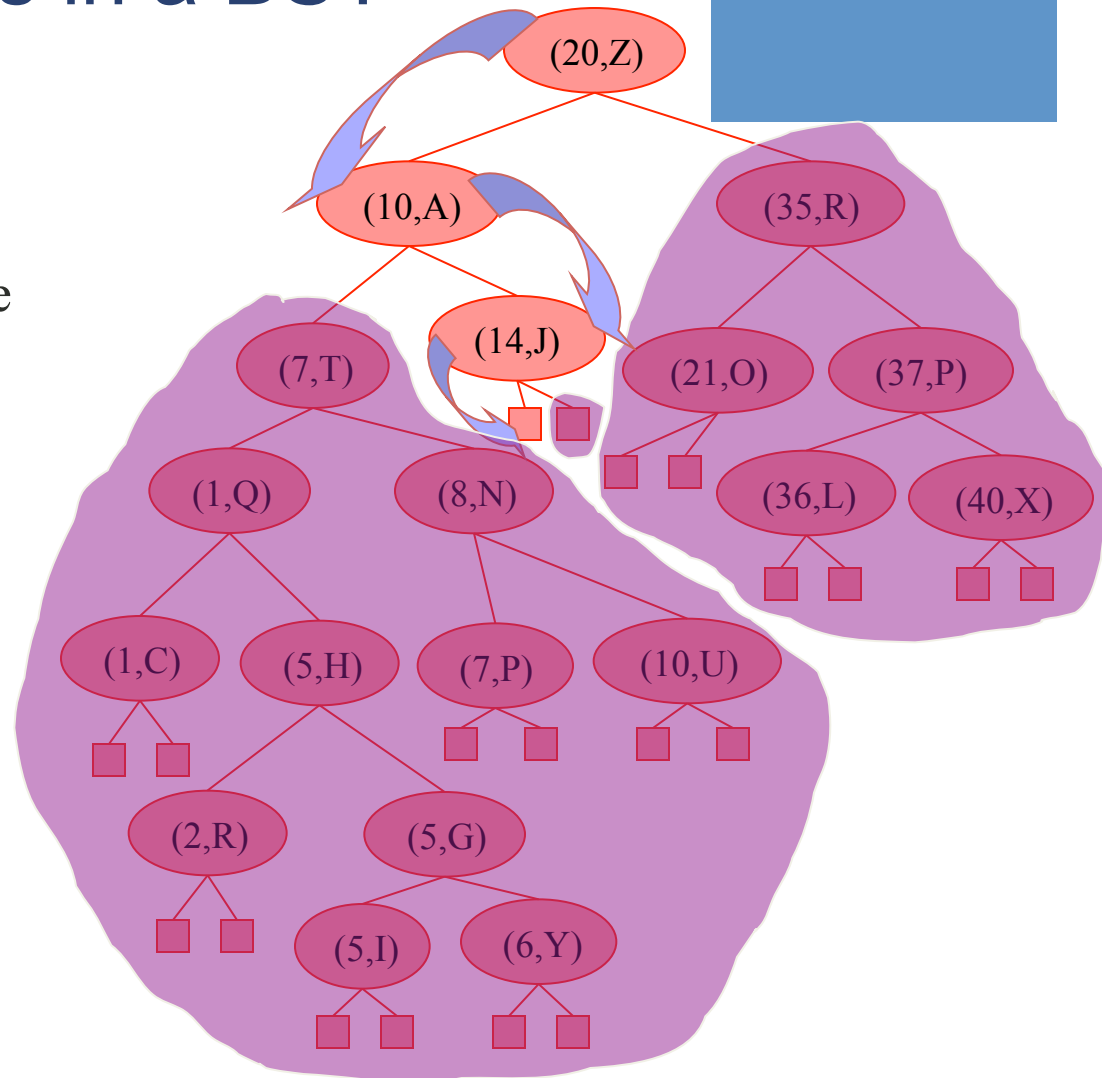
Splay Tree

- which nodes are splayed after each operation?

method	splay node
get(k)	if key found, use that node if key not found, use parent of ending external node
put(k,v)	use the new node containing the entry inserted
remove(k)	use the parent of the internal node that was actually removed from the tree (the parent of the node that the removed item was swapped with)

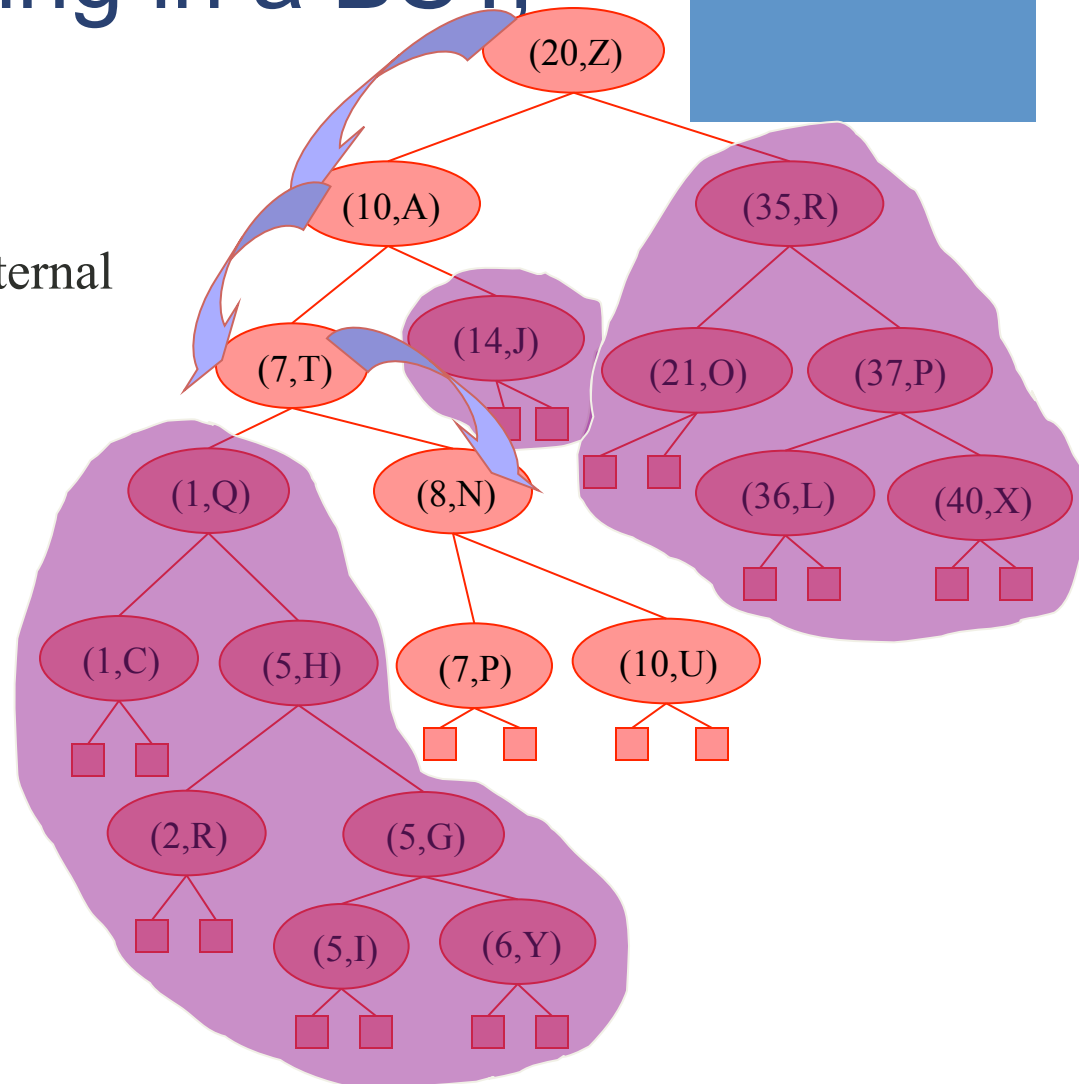
Searching in a Splay Tree: Starts the Same as in a BST

- Search proceeds down the tree to find item or an external node.
- Example: Search for the item with key 11.



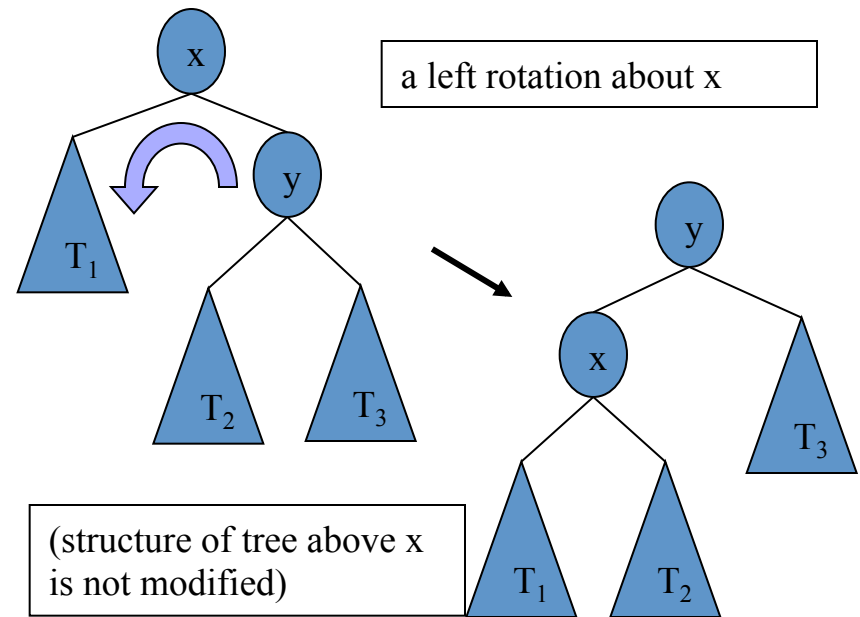
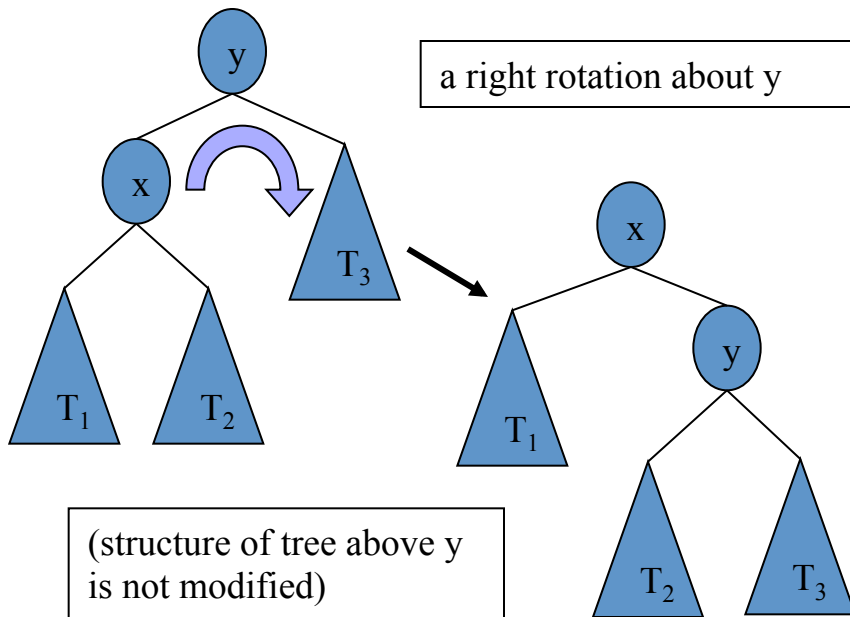
Example Searching in a BST, continued

- search for key 8, ends at an internal node.



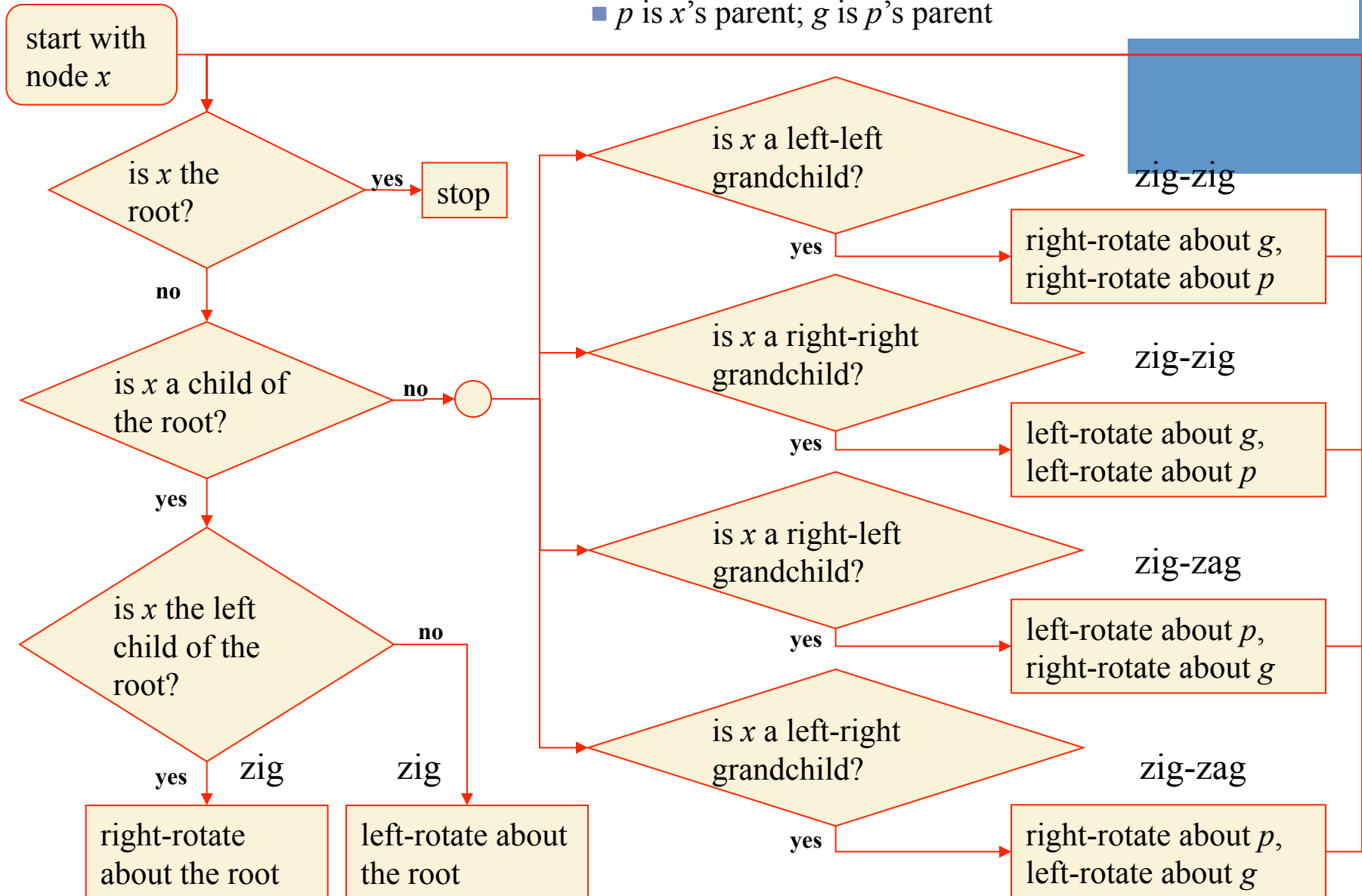
Splay Trees do Rotations after Every Operation (Even Search)

- new operation: *splay*
 - splaying moves a node to the root using rotations
- right rotation
 - makes the left child x of a node y into y 's parent; y becomes the right child of x
- left rotation
 - makes the right child y of a node x into x 's parent; x becomes the left child of y

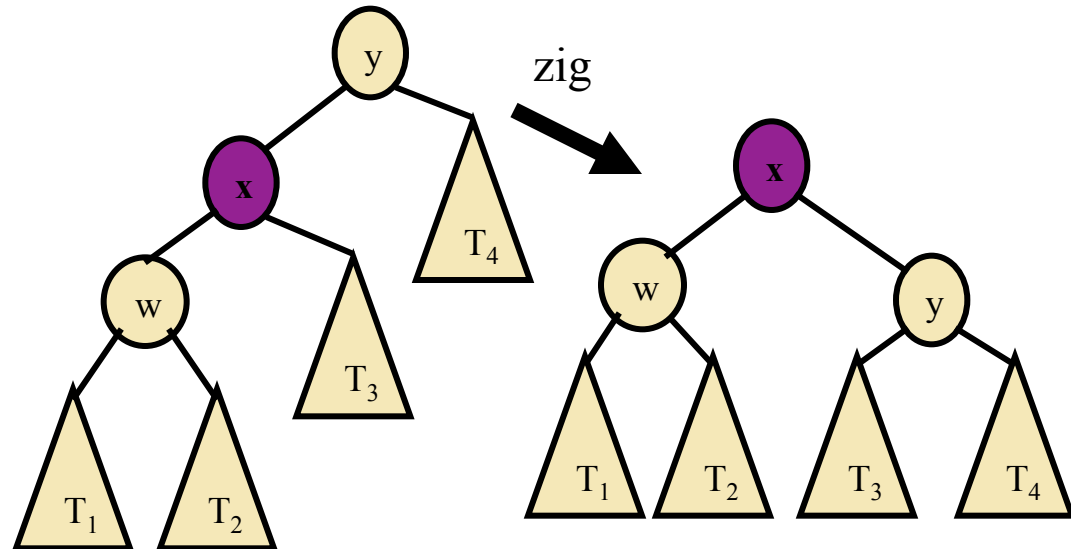
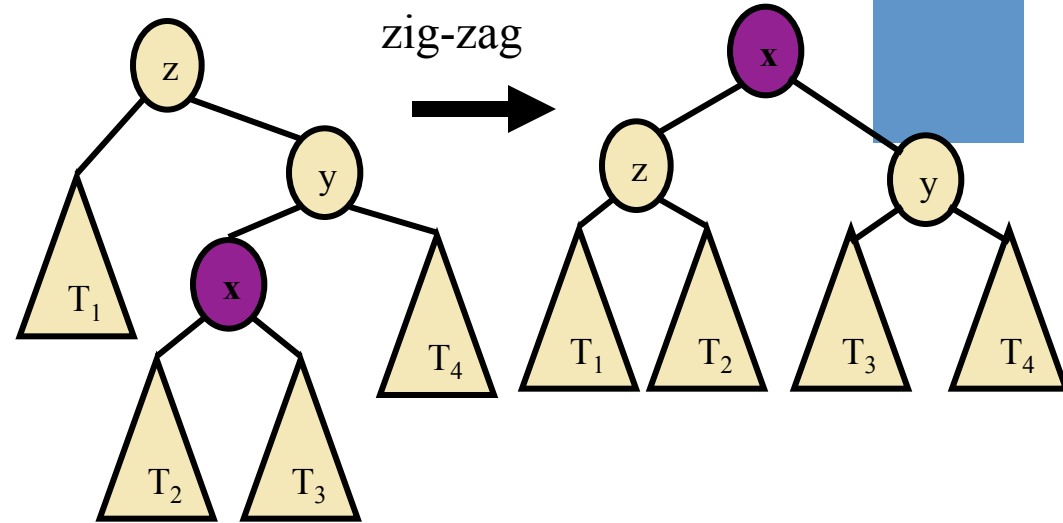
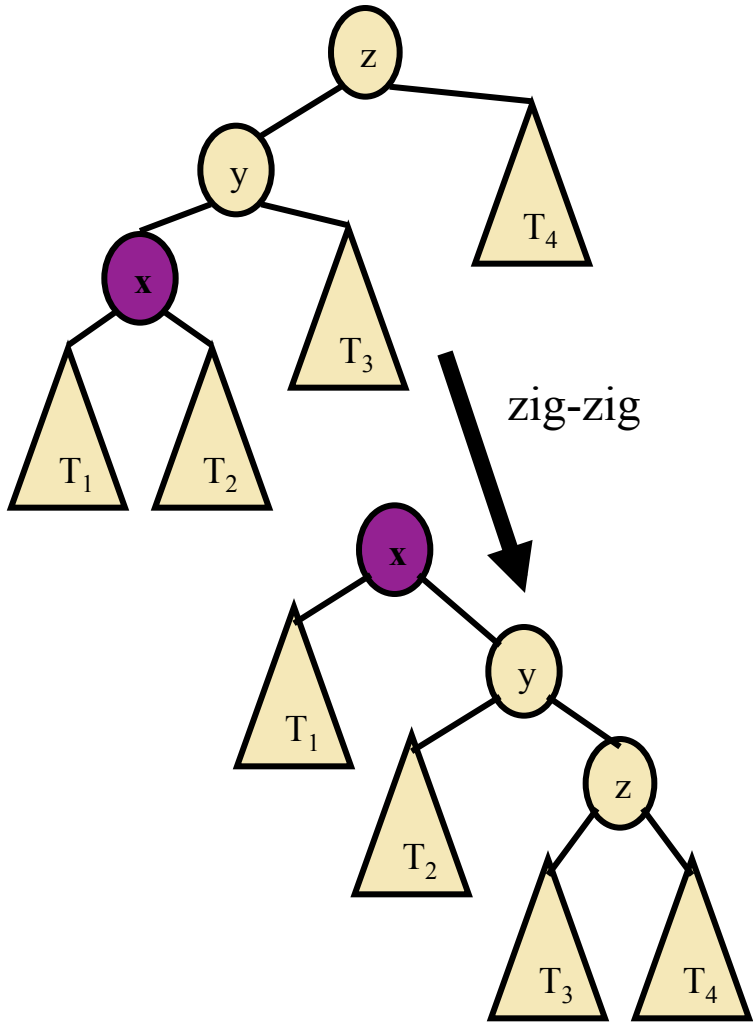


Splaying:

- “ x is a left-left grandchild” means x is a left child of its parent, which is itself a left child of its parent
- p is x 's parent; g is p 's parent

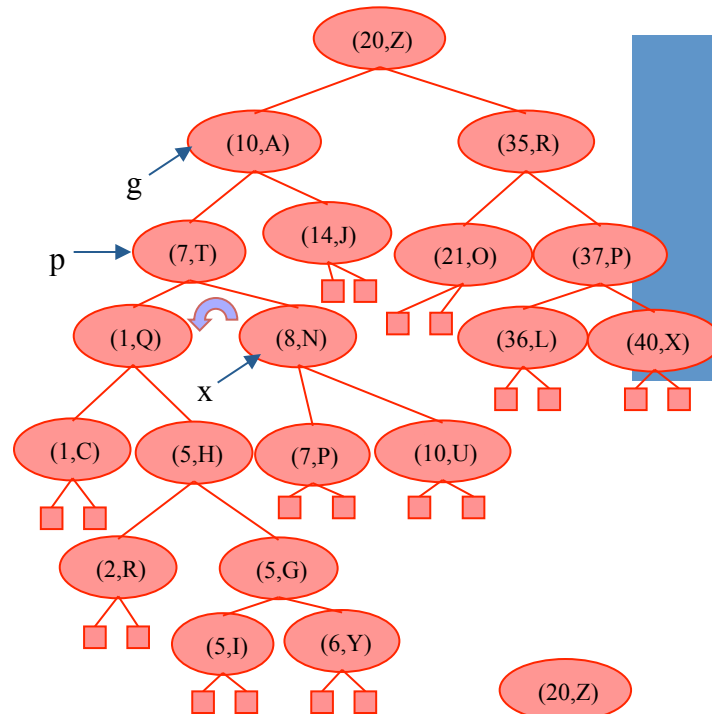


Visualizing the Splaying Cases

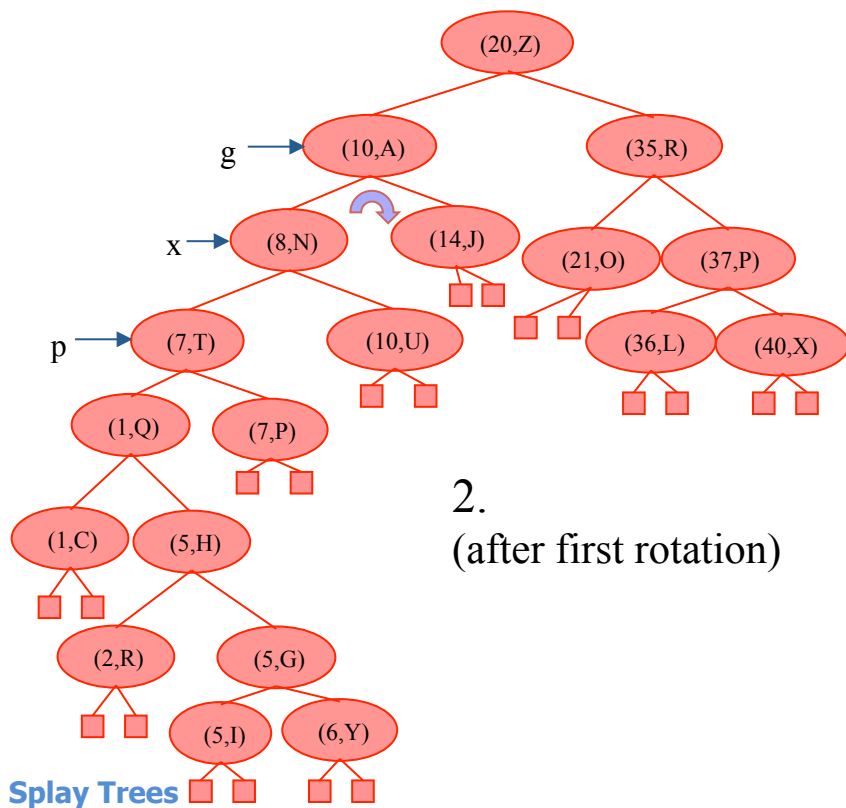


Splaying Example

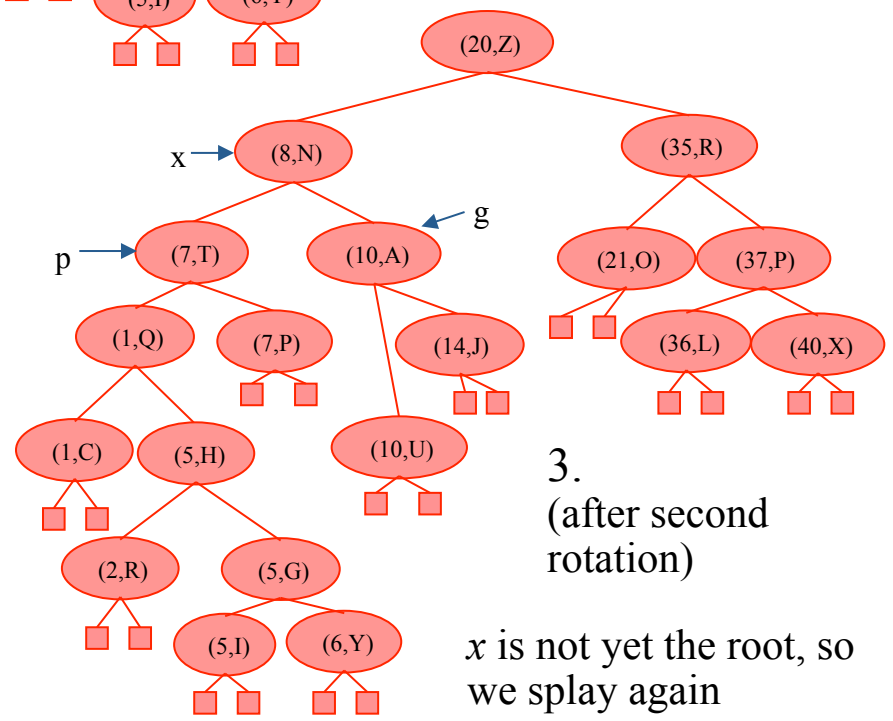
- let $x = (8,N)$
 - x is the right child of its parent, which is the left child of the grandparent
 - left-rotate around p , then right-rotate around g



31
1.
(before rotating)



2.
(after first rotation)

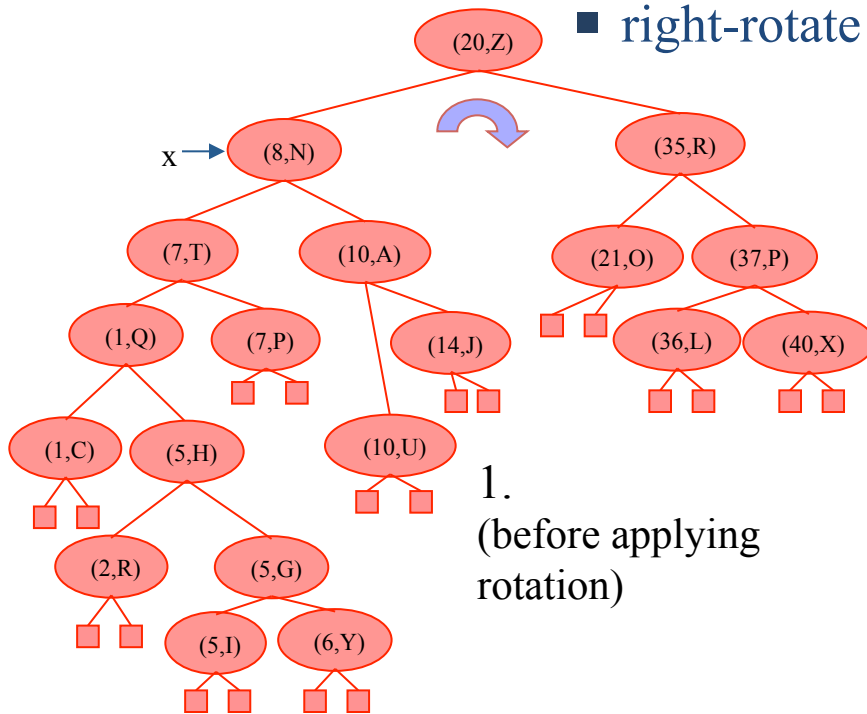


3.
(after second rotation)

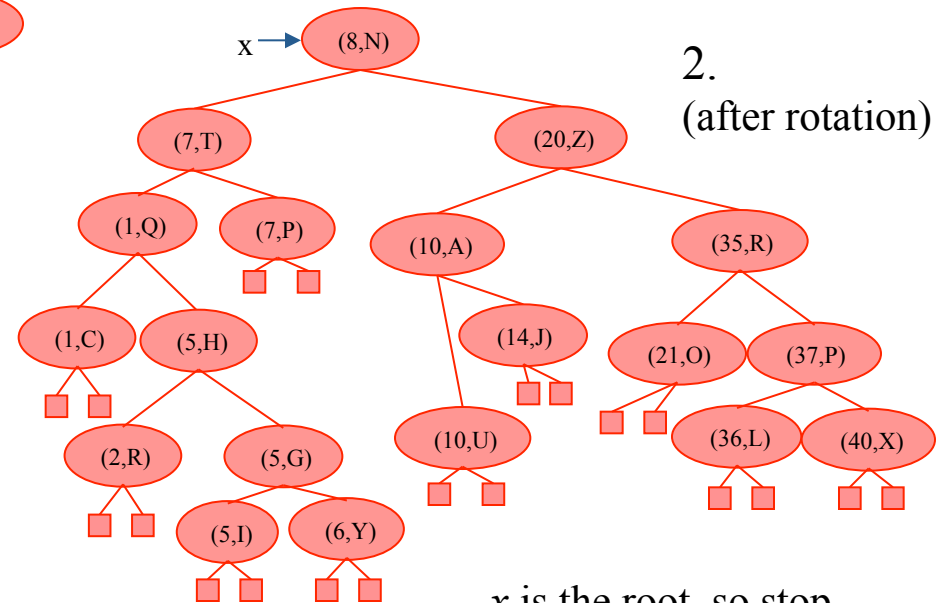
x is not yet the root, so we splay again

Splaying Example, Continued

- now x is the left child of the root
- right-rotate around root



1.
(before applying
rotation)



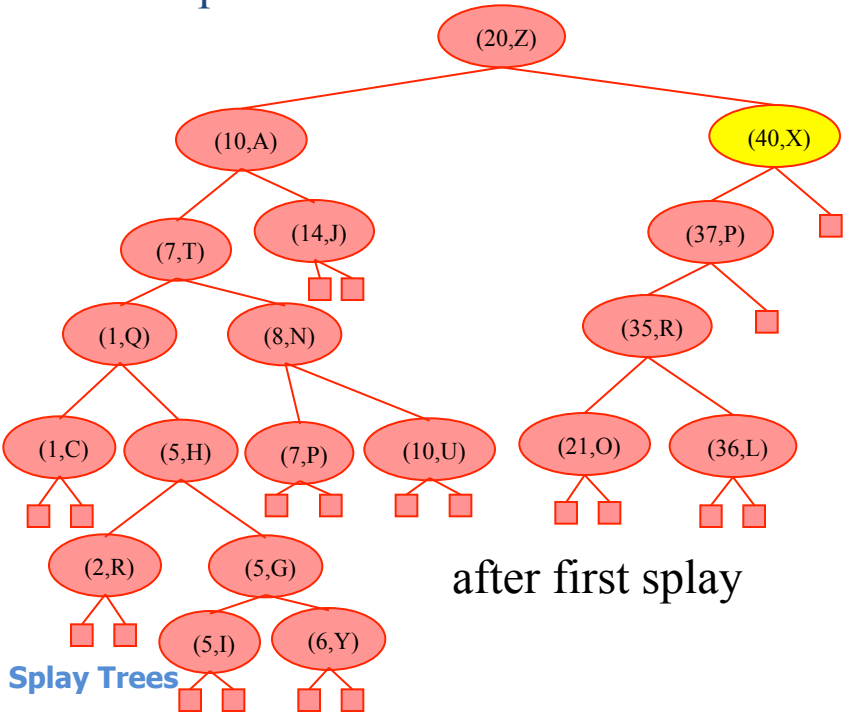
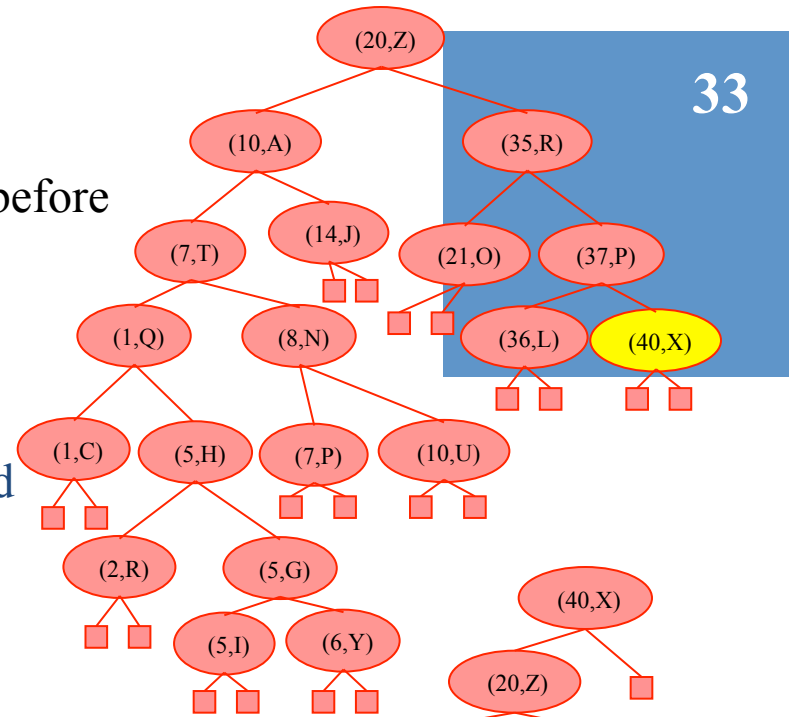
2.
(after rotation)

x is the root, so stop

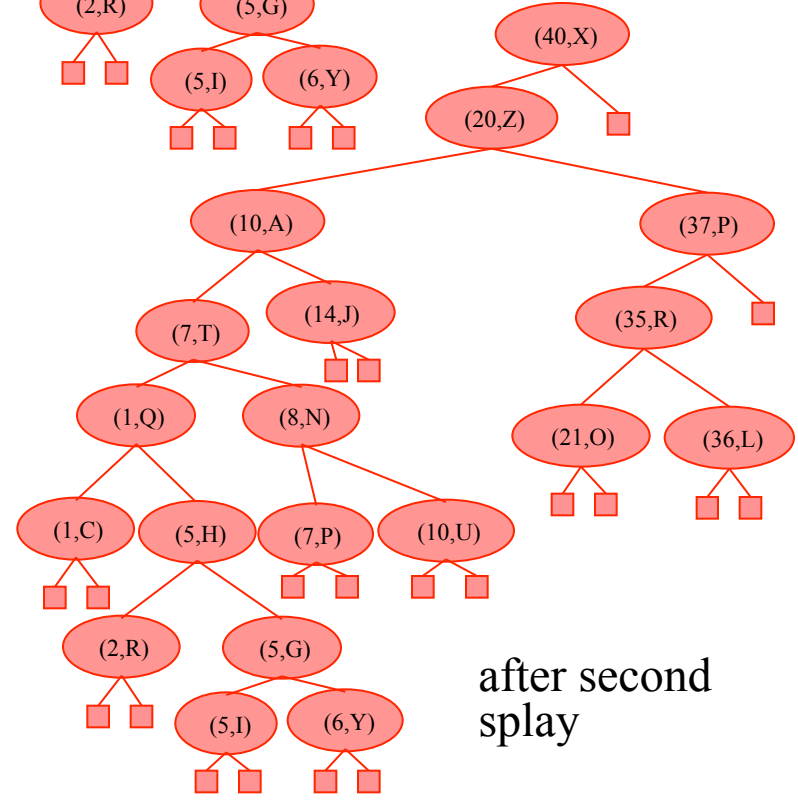
Example Result of Splaying

- tree might not be more balanced
- e.g. splay (40,X)
 - before, the depth of the shallowest leaf is 3 and the deepest is 7
 - after, the depth of shallowest leaf is 1 and deepest is 8

before



after first splay



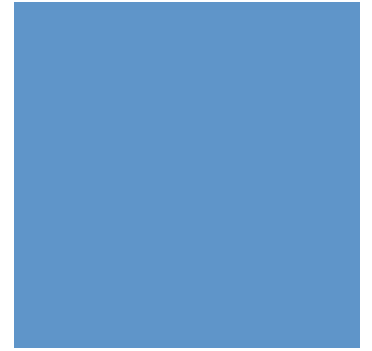
after second splay

Performance of Splay Trees

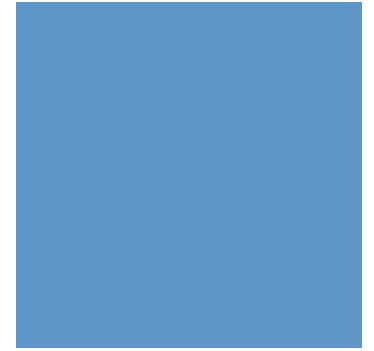
- Amortized cost of any splay operation is $O(\log n)$
- This implies that splay trees can actually adapt to perform searches on frequently-requested items much faster than $O(\log n)$ in some cases

Project Hints

- How to call google?
- How to find the reference links?
- How to encode Chinese?



HW10 (Due on Dec. 24)



Use Google and get the links!

- Get a keyword from user
- Return the urls listed in the search result
- Save the results in a hash table (we will discuss it in the next lecture)

- After this HW, you can step to the forth stage of the project
- You can apply the same technique to other search engines

Coming Up

- Binary Search Trees
 - TB Chapter 10
- Maps and Hash tables
 - TB Chapter 9 and 10

